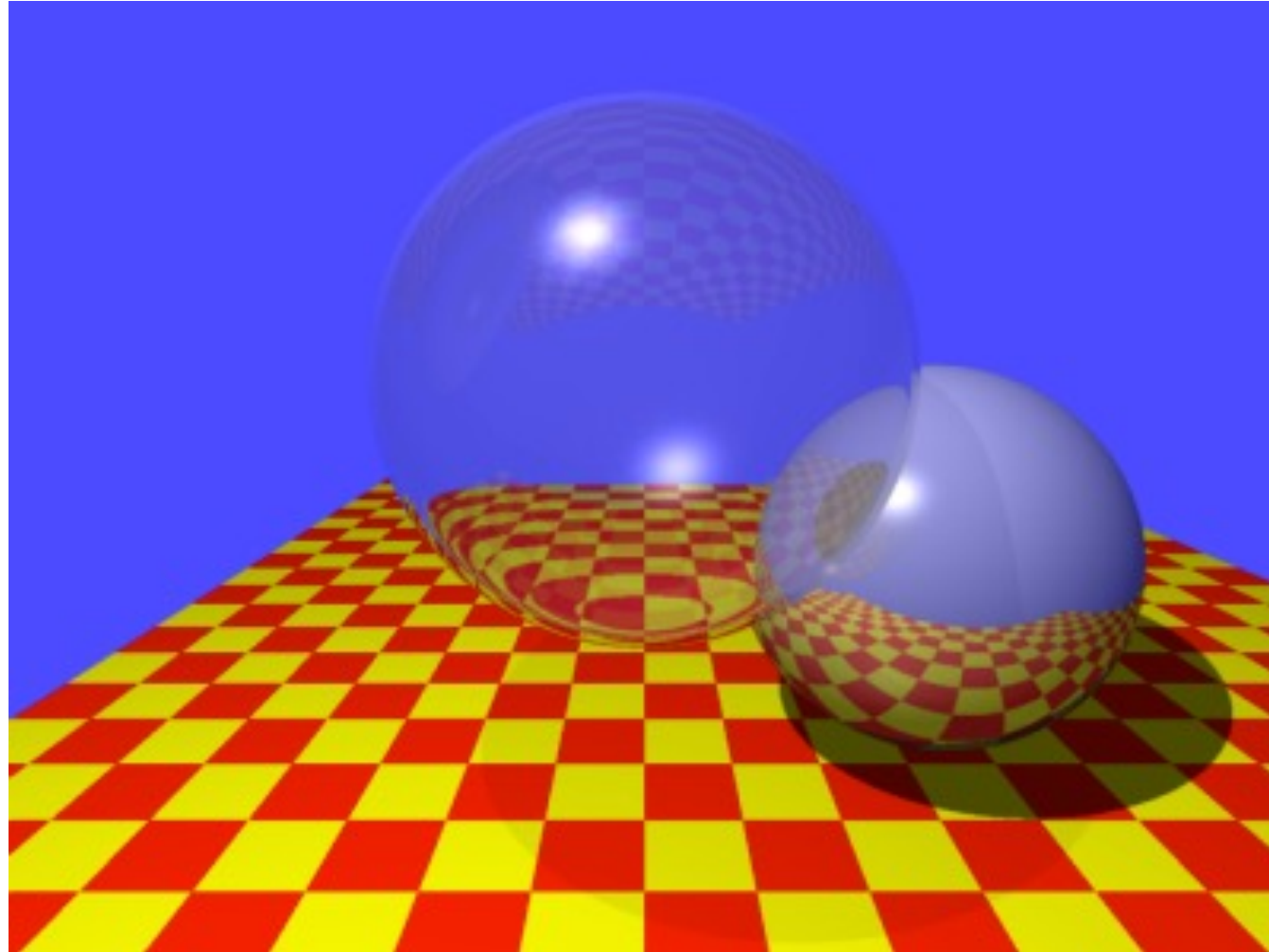


13 – raytracing (1)

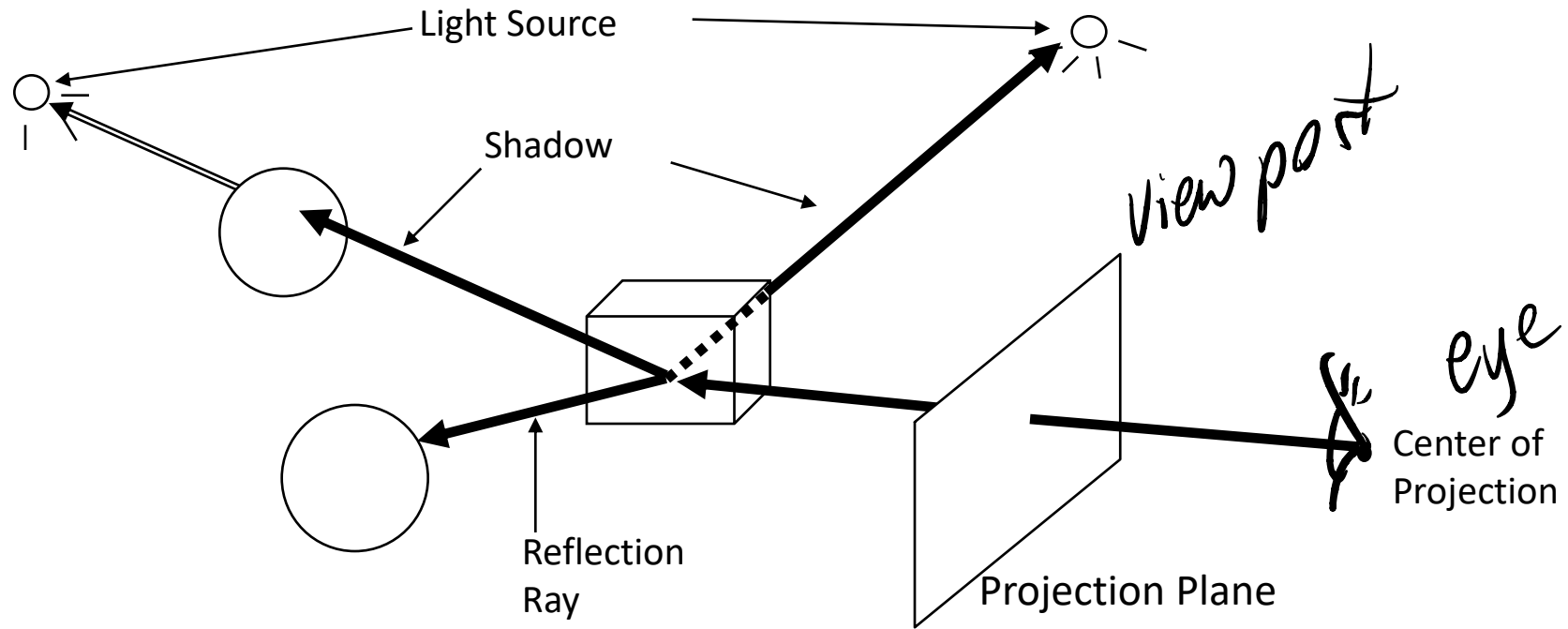
3 approaches to graphics

- On-line / “real-time” *WebGL in general*
 - Immediate mode
Raw WebGL calls
 - Retained mode / *Scene Graphs/etc*
- Off-line / batch / “slow”

Ray Tracing 1980s a way to deal with shadows & hidden surfaces
Whitted



Basic Idea



Basic Algorithm

for each pixel (x_s, y_s)

create a ray R from eye through (x_s, y_s)

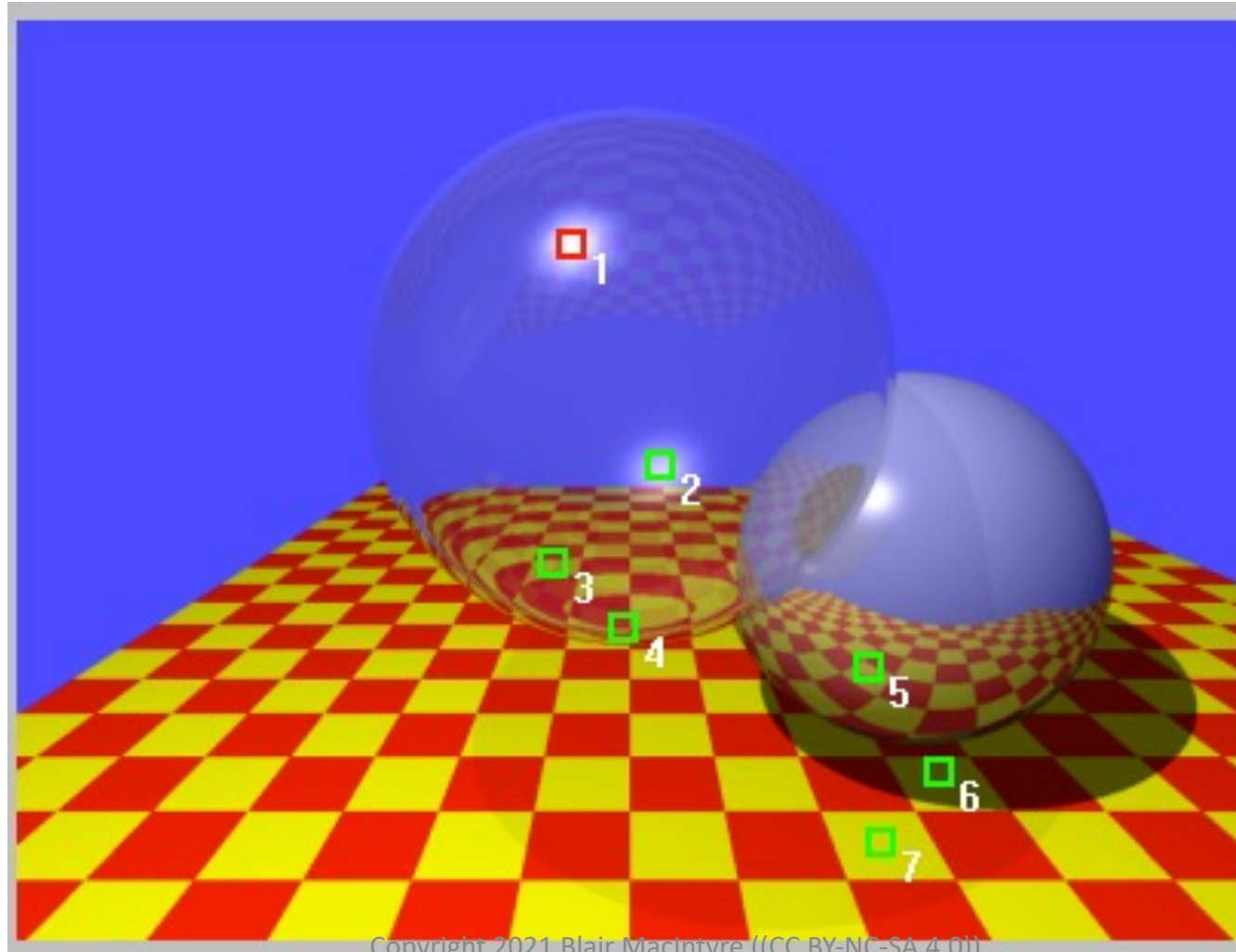
for each object O_i in scene

[if R intersects O_i & it's the closest
so far

[record this intersection

shade pixel based on nearest intersection
(recursively for ref & transmission)

The Adventures of 7 Rays



Basic Algorithm

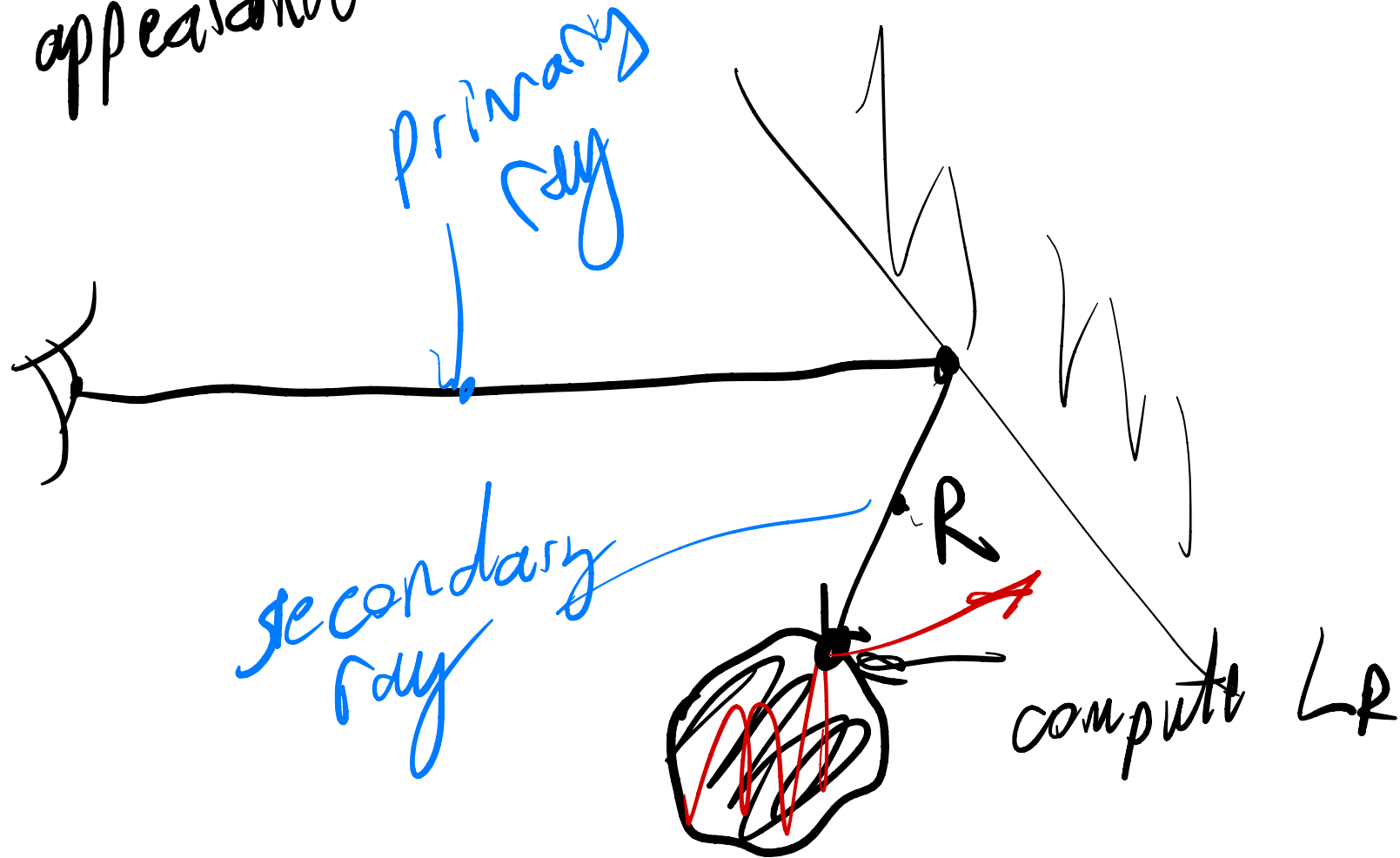
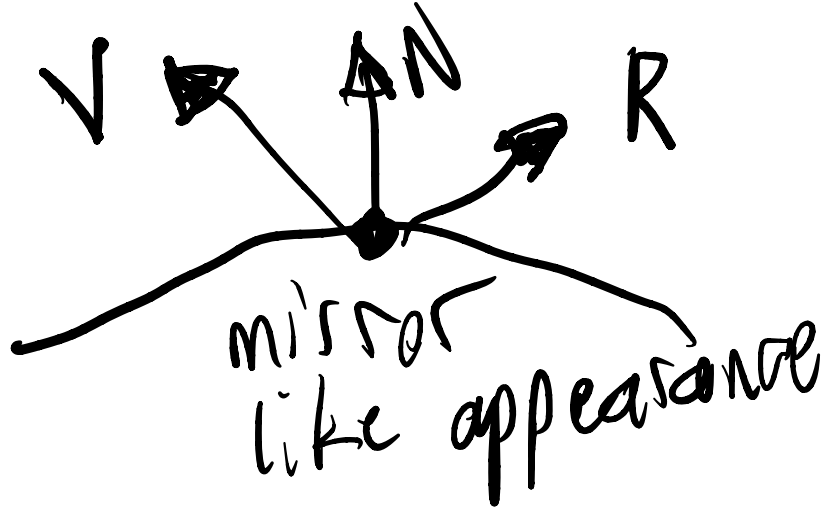
Illumination of a point

ambient

$$L = k_a I_a + k_s L_r + k_r L + \sum_{1 \leq i \leq N} S_i I_i [k_d (N \cdot L_i) + k_s (R_i \cdot V)^{p_i}]$$

reflected *refracted* *previous eq*

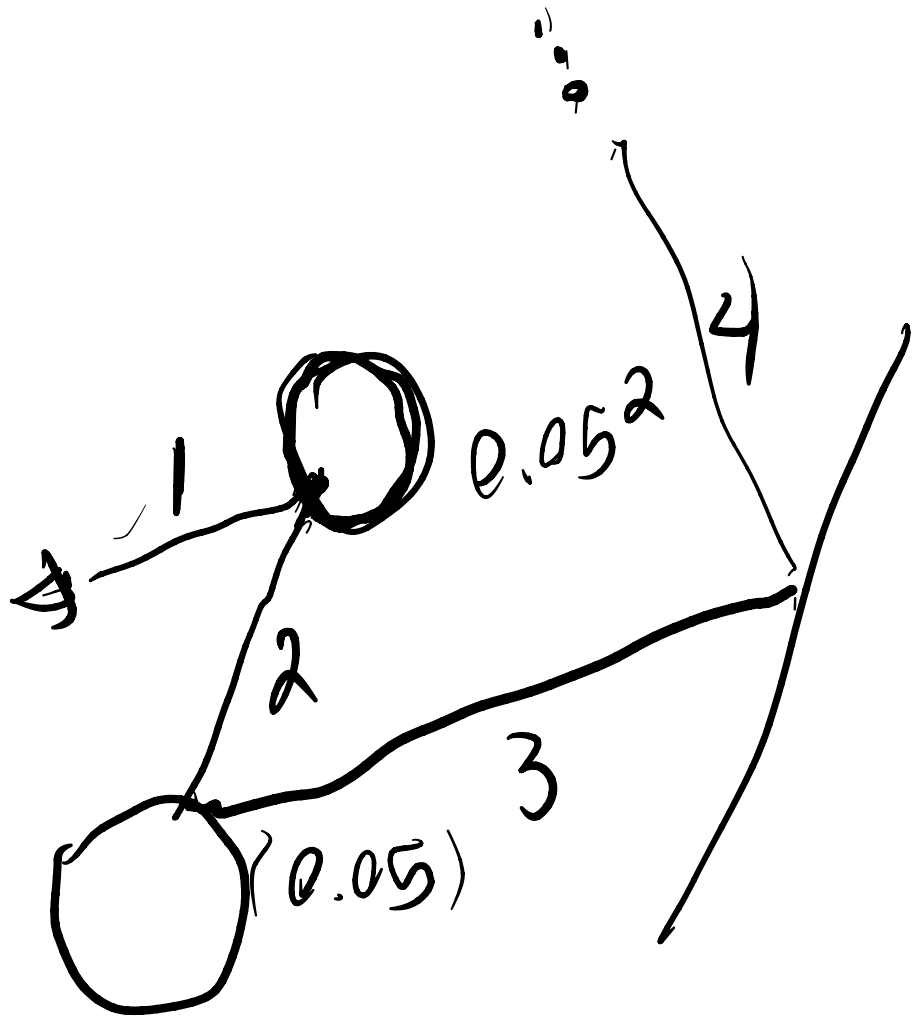
$S_i = \begin{cases} 0 & \text{— if shadow ray (light ray) is blocked} \\ 1 & \text{— if not blocked (reached light)} \end{cases}$



ambient + diffuse + specular + $k_r L_r$ + $k_t L_t$

how reflective?

how trans



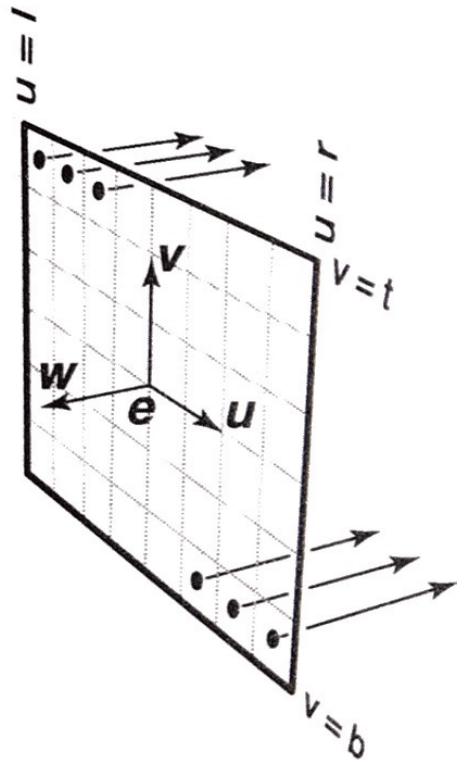
shoot Ray (R) \rightarrow L

when to stop?

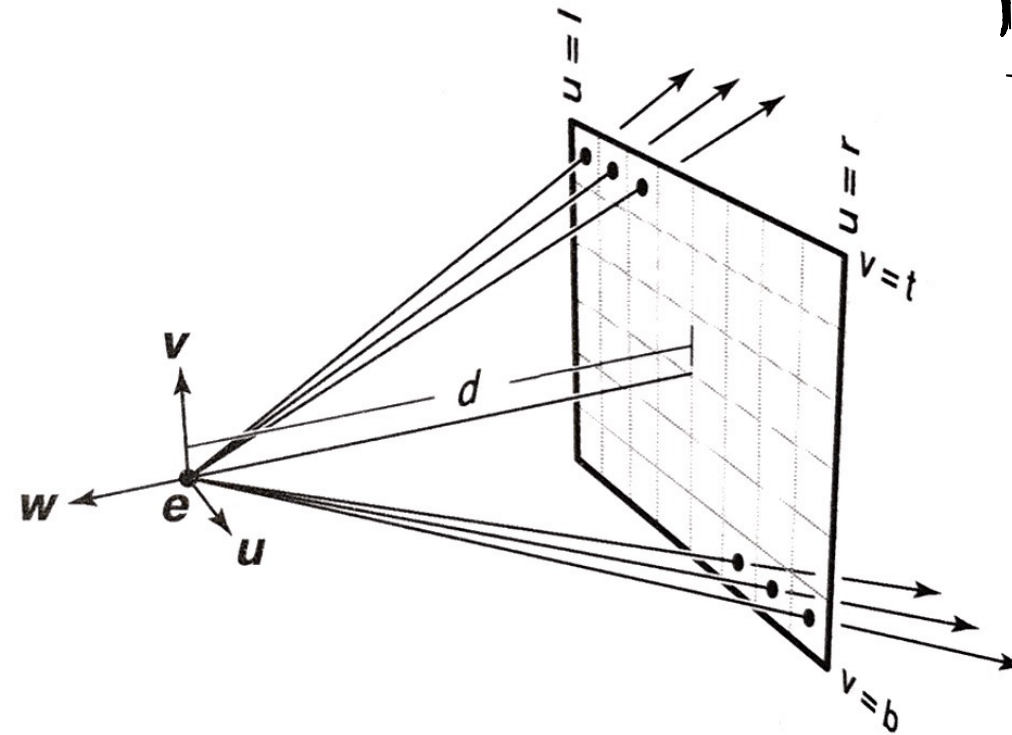
- 1) set max recursive step
- 2) contribution of ray is small

Eye Rays: Depends on Projection (Orthographic, Perspective, Oblique)

fov



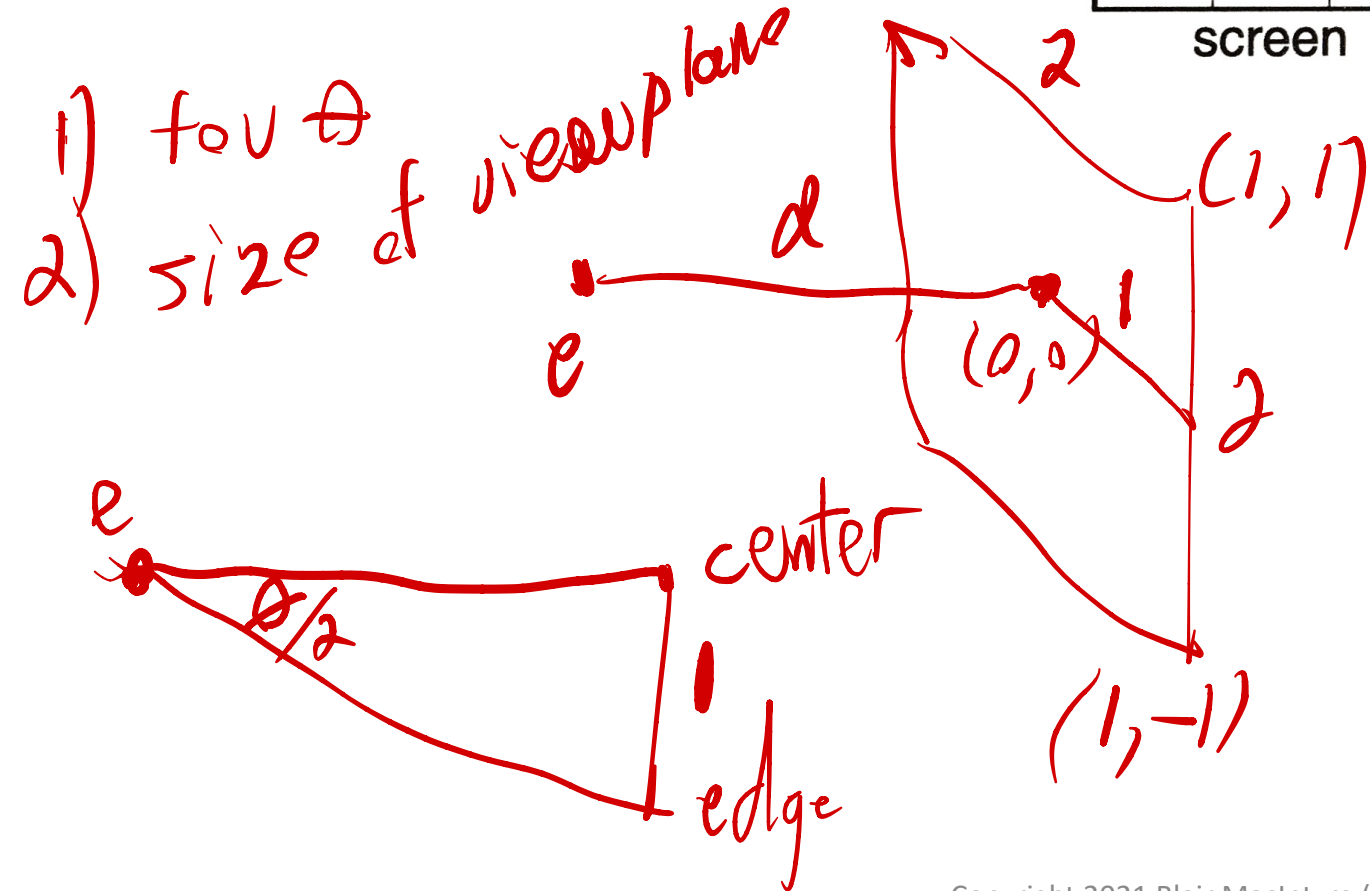
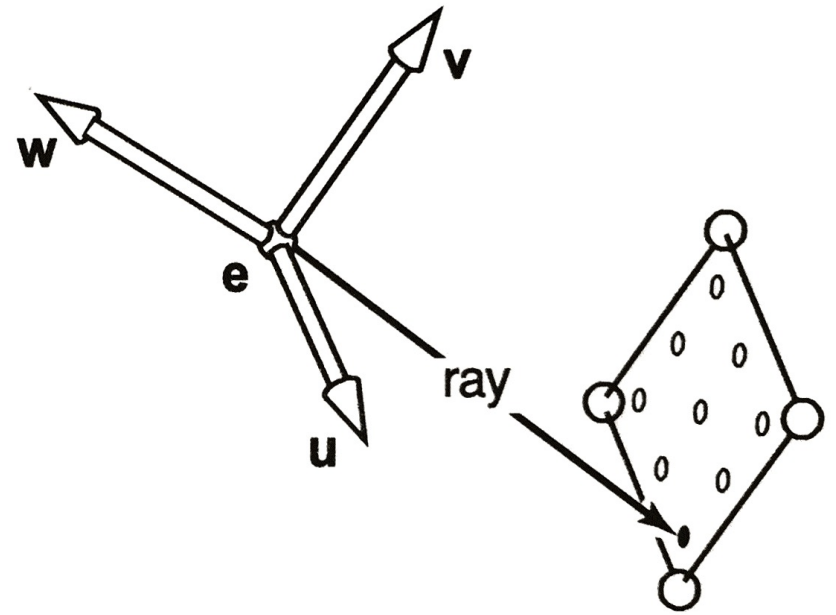
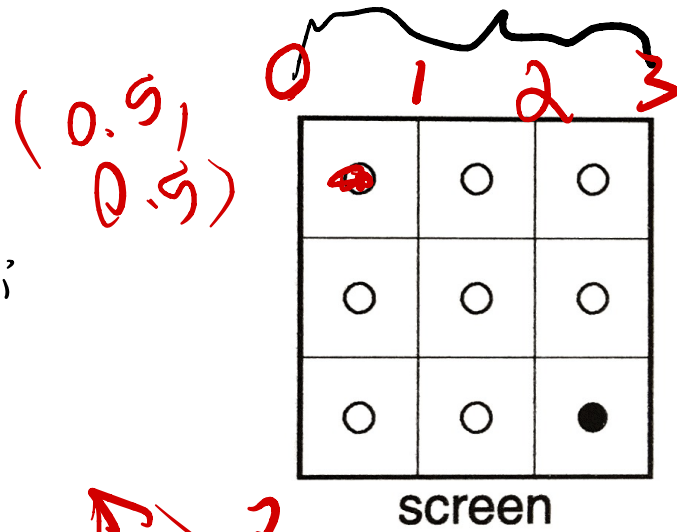
Parallel projection
same direction, different origins



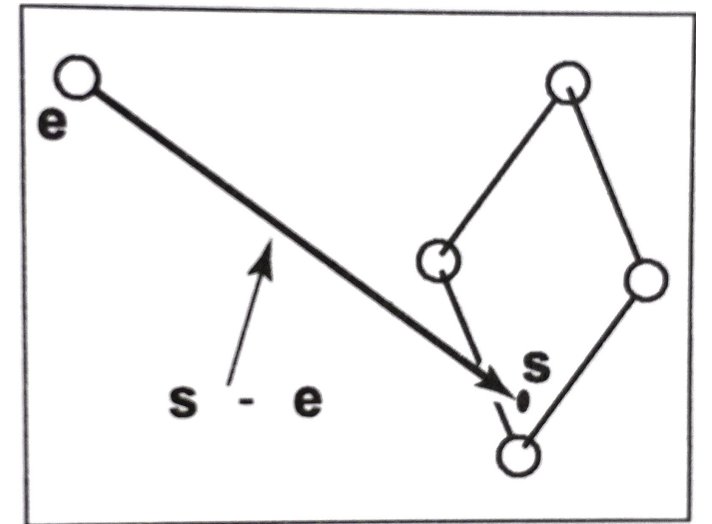
Perspective projection
same origin, different directions

parametric eq'n:

$$p(t) = e + t(s - e)$$



$$d = \frac{1}{\tan(\frac{\theta}{2})}$$



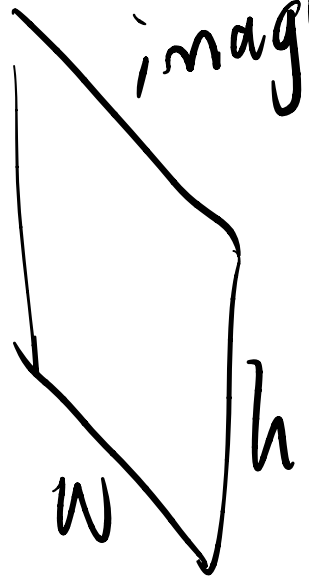
$$u_s = -1 + \frac{2i}{h}$$

$$v_s = -1 + \frac{2i^w}{h}$$

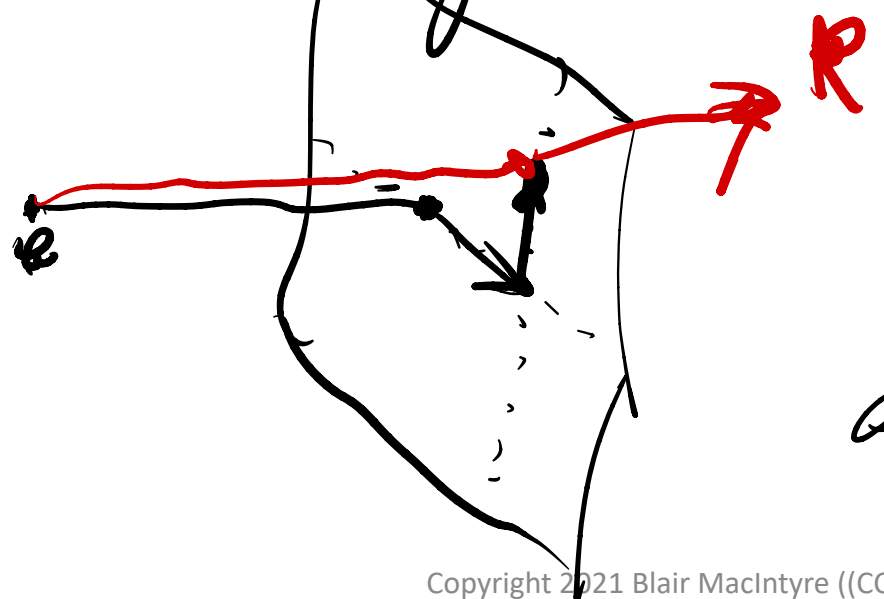
image

u & v
 -1 radii range

u
 v
 w



ray direction = $\frac{s - e}{|s - e|}$



$$= -dw + u_s u + v_s v$$

origin = e

for

for $i = 0$ to $w-1$
for $j = 0$ to $h-1$
compute $R(u_s, v_s)$ using (i, j)
shoot Ray (R)

(Note: An arrow points from the (i, j) in the second line to the (i, j) in the third line, indicating that the second line's j is not i .)

Computing Intersections

different for each object

- sphere is easy
- polygons are easy
- objects mesh (compute per triangle)
- implicit surfaces

$$p(t) = e + td \quad d = s \cdot e \quad \text{canonical sphere}$$

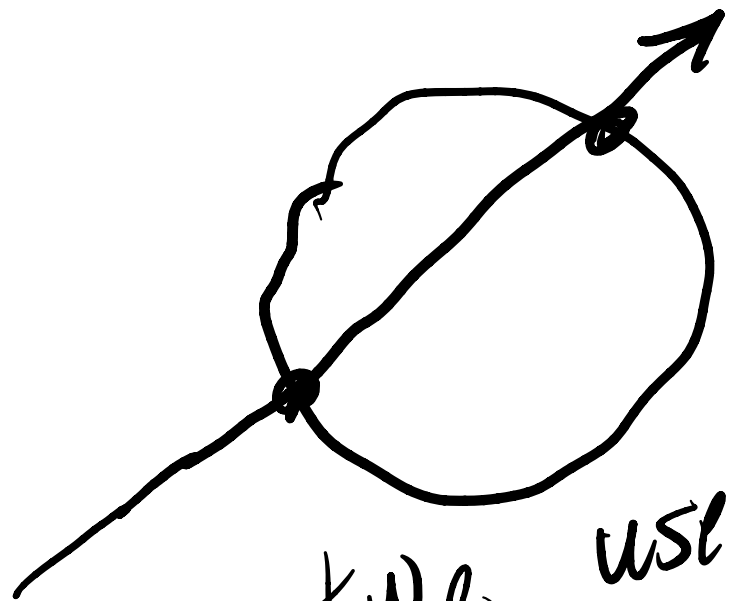
Sphere/Ray Intersections

center at $(e, 0, 0)$
radius of 1

$$x^2 + y^2 + z^2 = 1^2$$

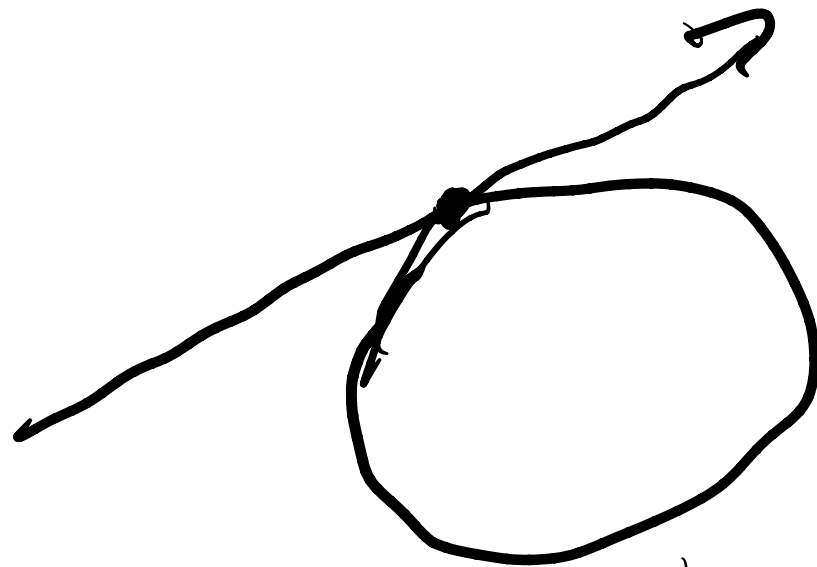
$$(x_e + t d_x)^2 + (y_e + t d_y)^2 + (z_e + t d_z)^2 = 1$$

$$t^2 (d_x^2 + d_y^2 + d_z^2) + t 2(x_e d_x + y_e d_y + z_e d_z) + (x_e^2 + y_e^2 + z_e^2 - 1) = 0$$
$$t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

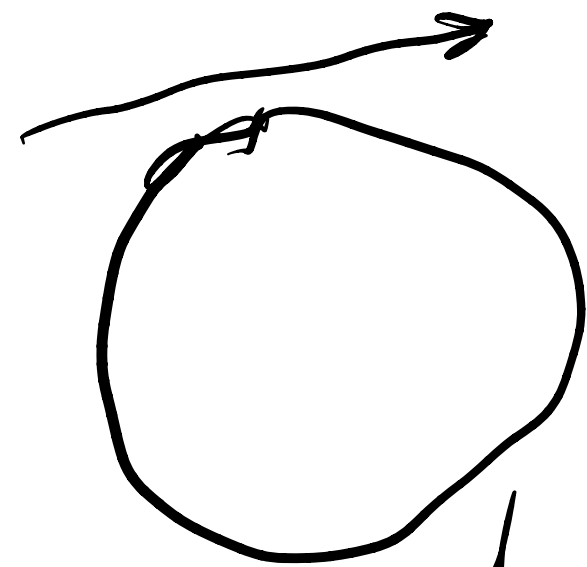


two, use
closest

general case



one root

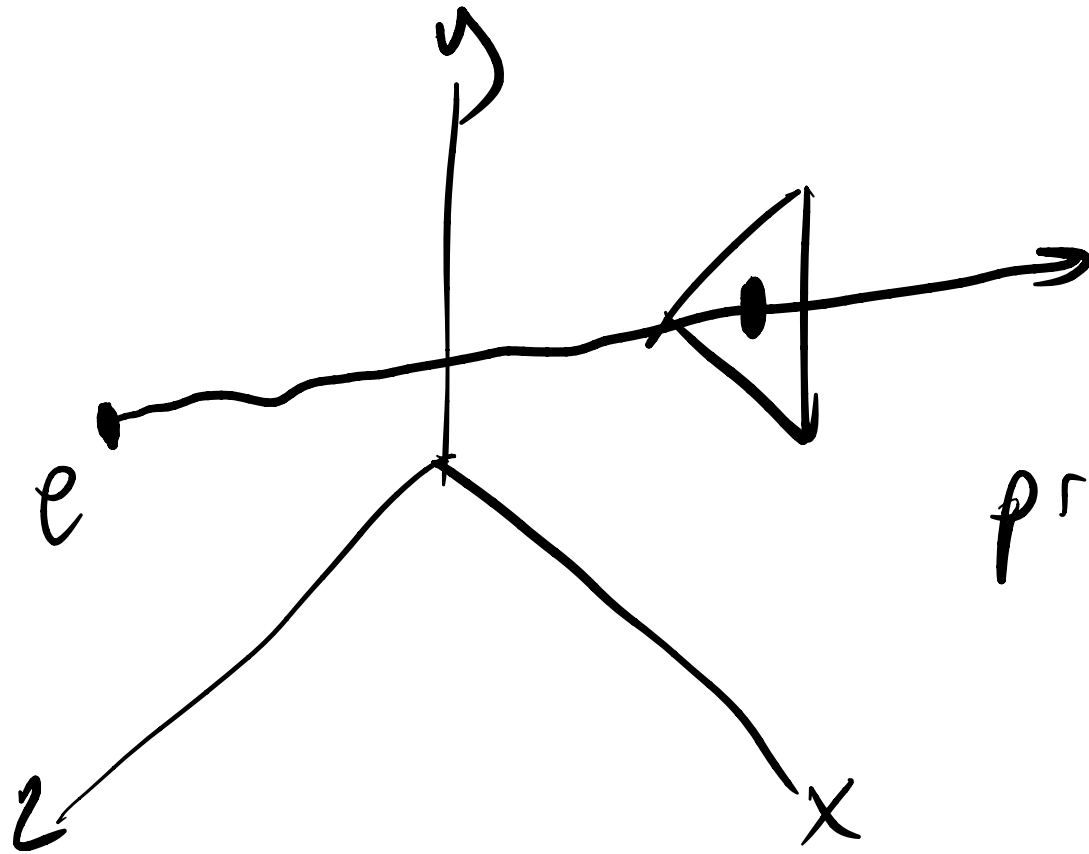


no real
roots

center = (x_c, y_c, z_c)
radius = R

$$(x - x_c)^2 + (y - y_c)^2 + (z - z_c)^2 = R^2$$

Ray/Triangle Intersection



compute intersection
at R with the
plane of the
triangle

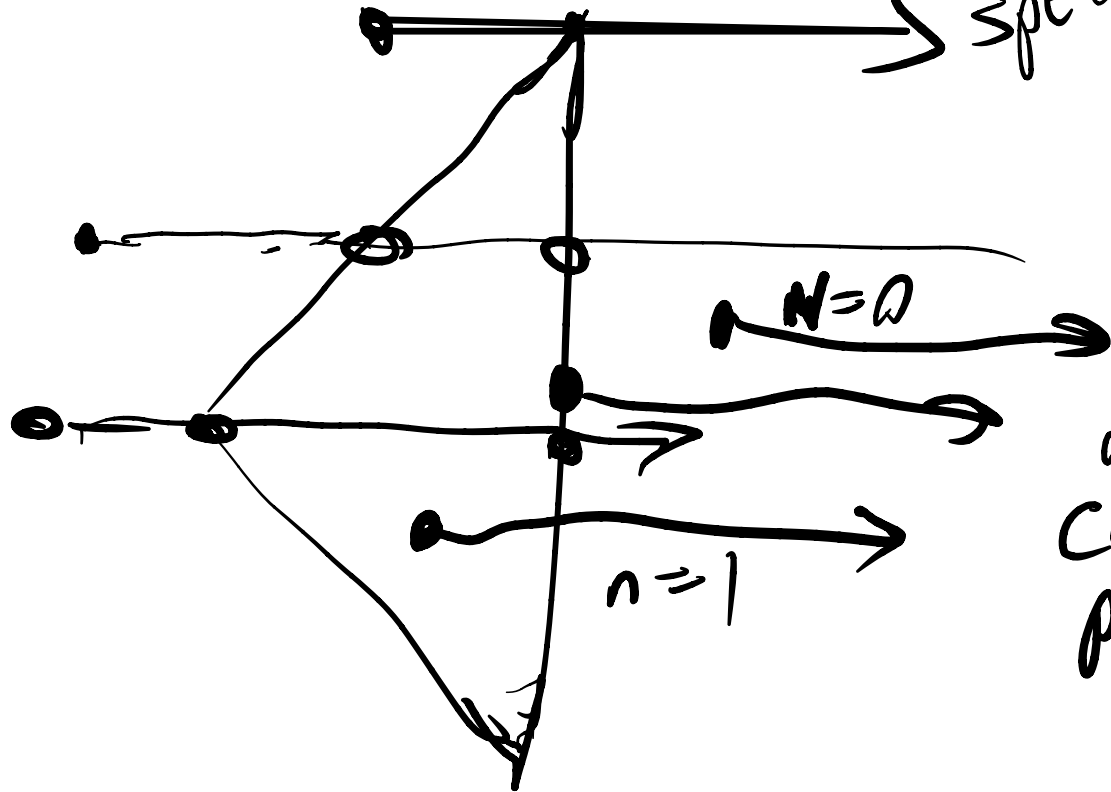
project to 2D

→ going to xy , xz ,
or yz planes

based on Normal of plane
the largest of (n_x, n_y, n_z)

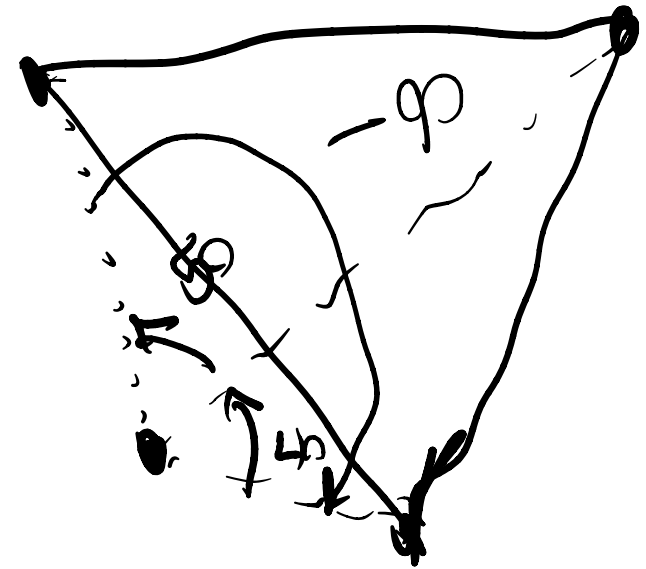
Point in Triangle in 2D

deal with special cases



any convex polygon too!

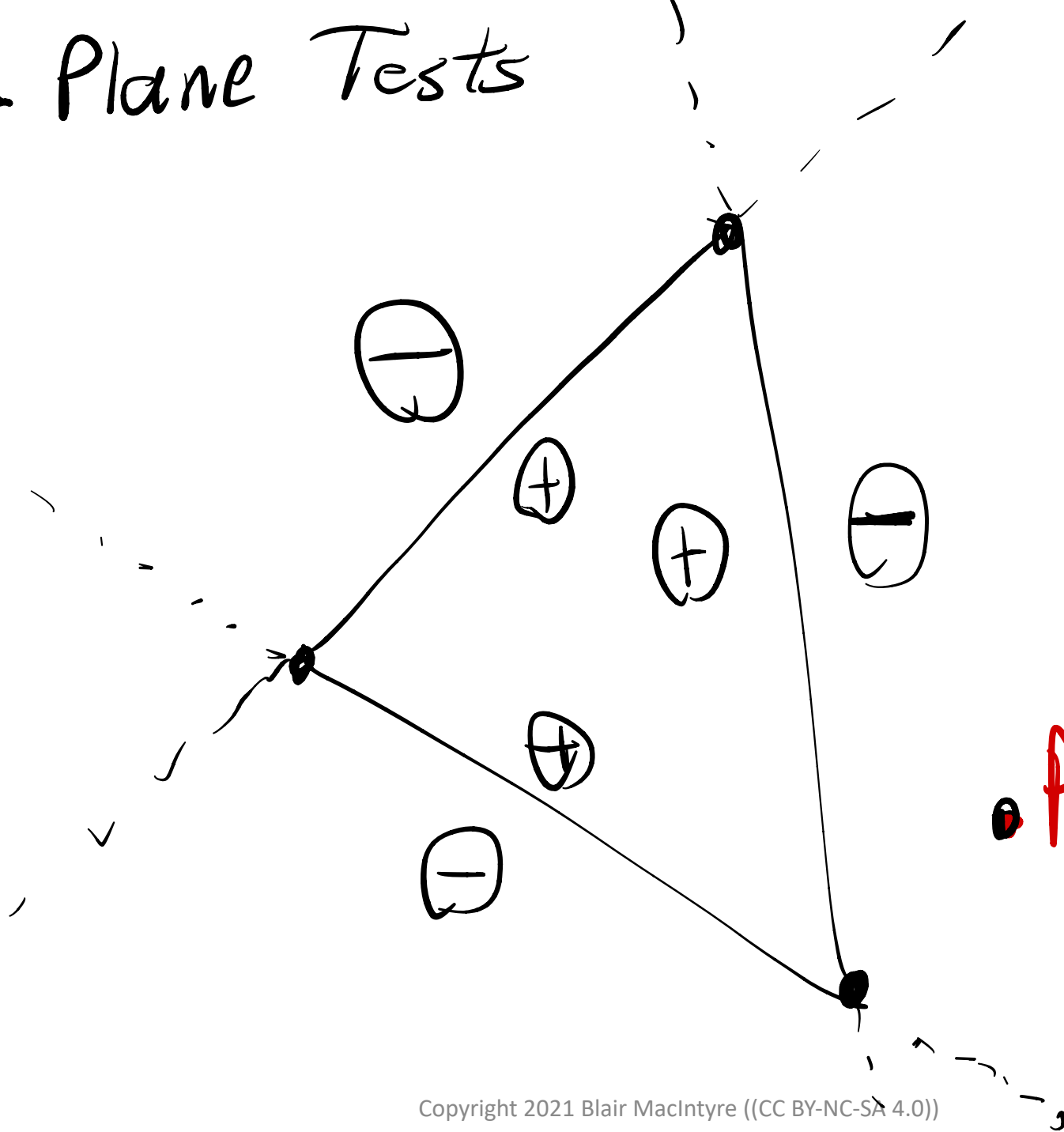
even number, outside
odd, inside



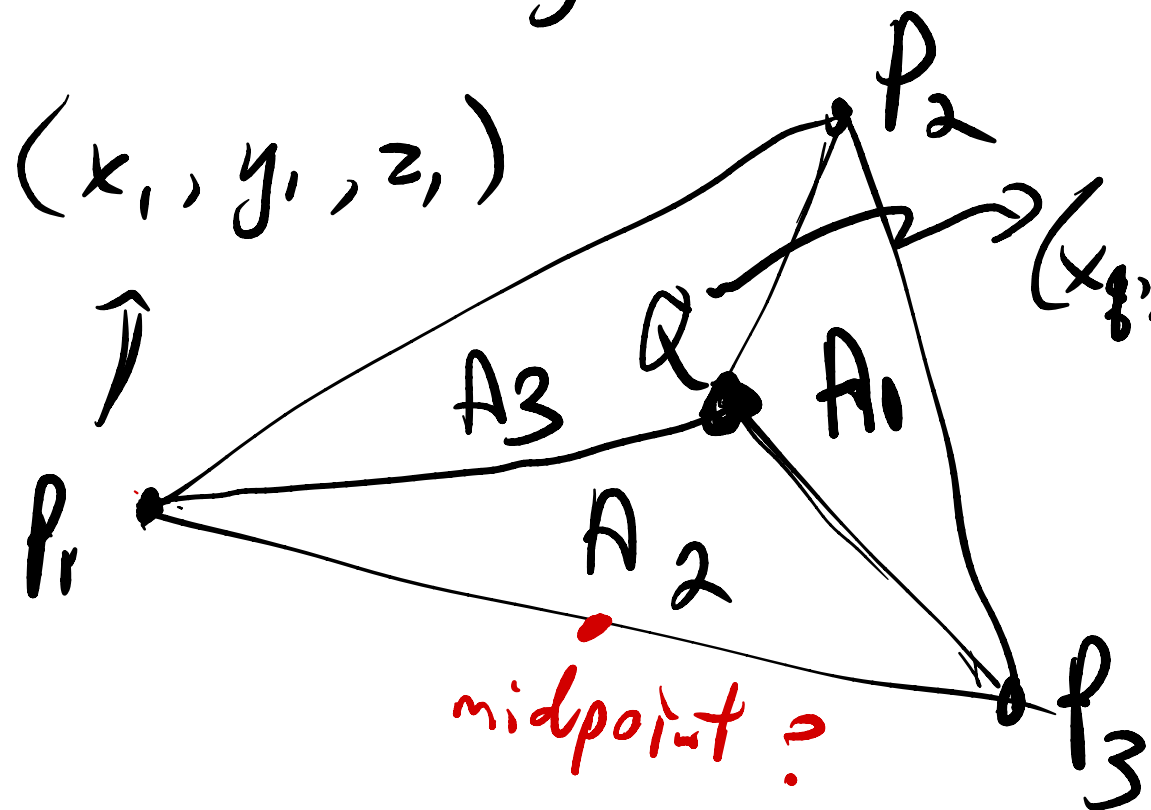
$$40 + 50 - 90 = 0$$

Half-Plane Tests

compute implicit
line equation
for each
line



Barycentric Coordinates



$A_1 =$ area of sub-triangle opposite P_1
 $(A_2, A_3) \dots$

$$A = A_1 + A_2 + A_3$$

$$\alpha = A_1 / A$$

$$\beta = A_2 / A$$

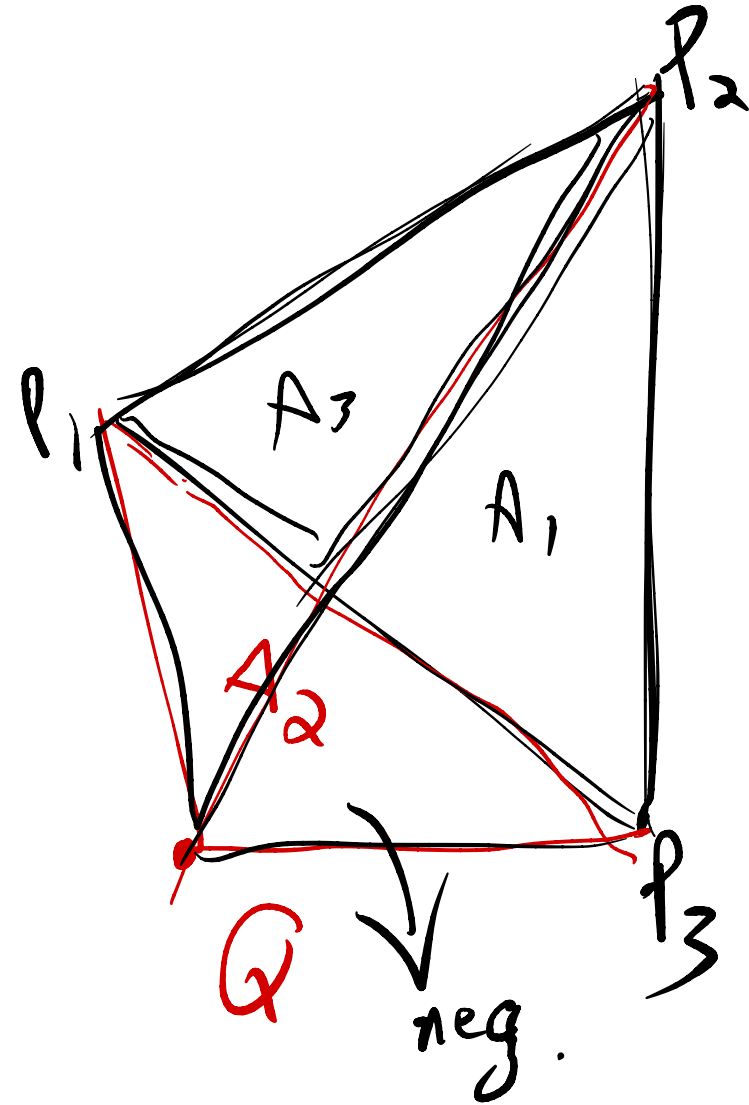
$$\gamma = A_3 / A$$

$$\alpha + \beta + \gamma = 1$$

$$Q = \alpha P_1 + \beta P_2 + \gamma P_3$$

$$Q = \alpha P_1 + \beta B_2 + \gamma P_3$$

α, β, γ are positive inside tri
one or more negative if point is outside



Computing Plane Intersection: Implicit Line Equation

