

(polygons)

7 – triangles and hidden surfaces

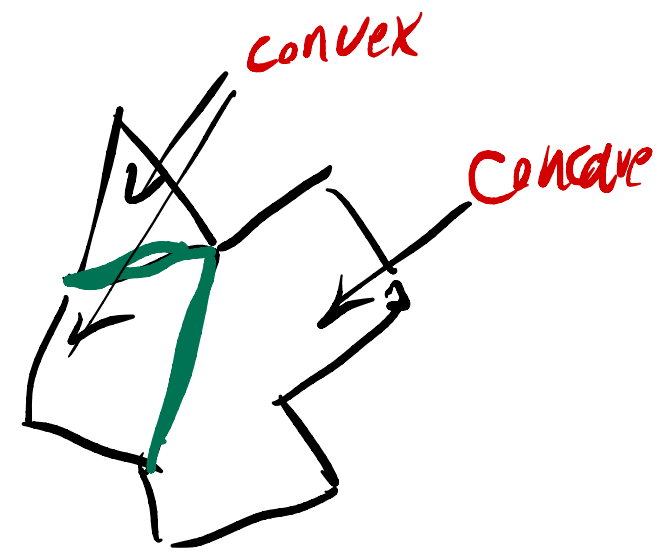
Rasterizing triangles

Hidden / visible surface algorithms

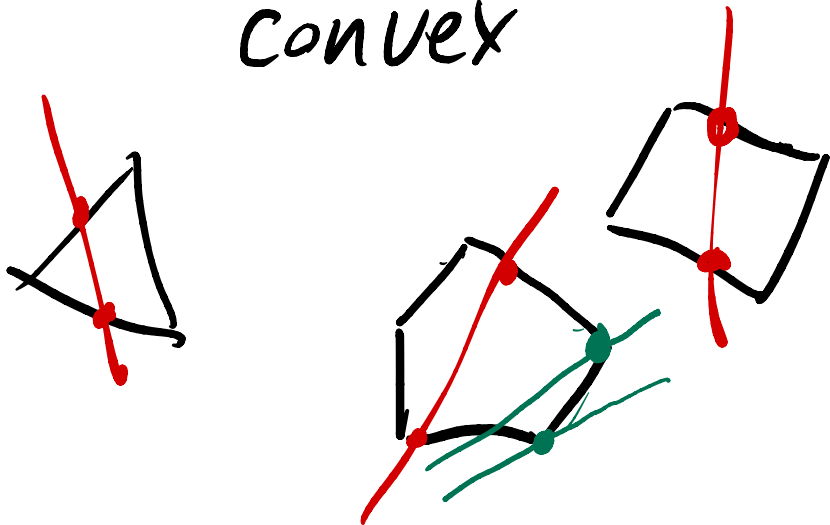
Polygons & Rasterization

Goal: no cracks between adjacent polys
no overlaps

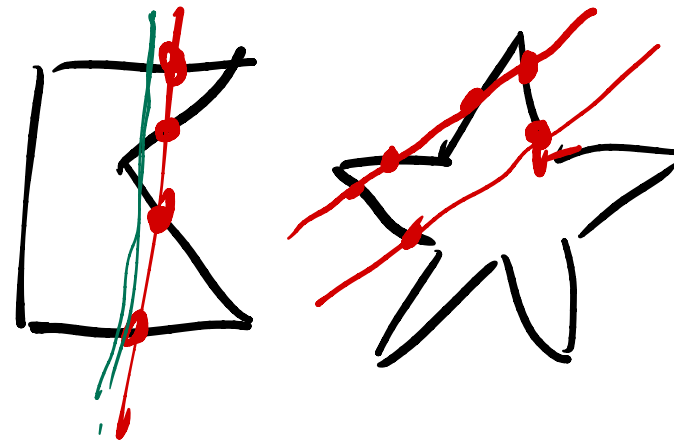
GPU's are optimized for polygons
(triangles)



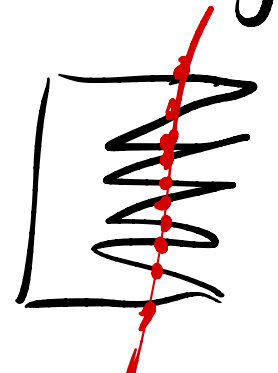
convex



concave



algs
focus on
drawing
between
2 edges

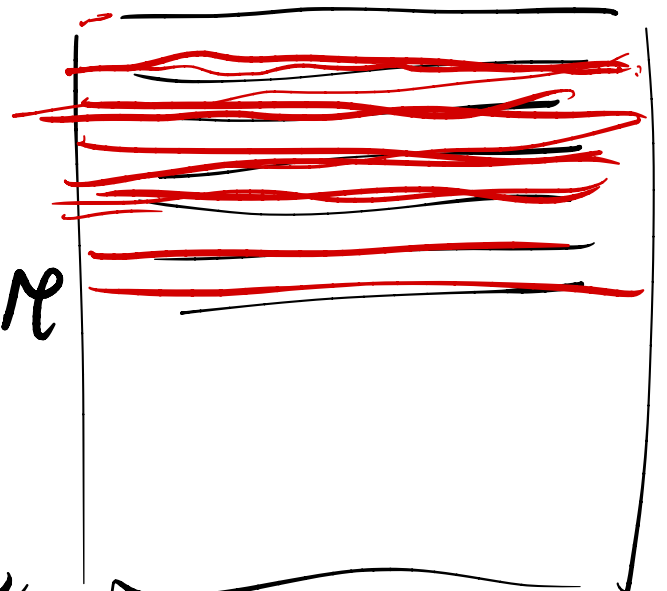


Rasterization \Rightarrow Scan Conversion

fill a polygon

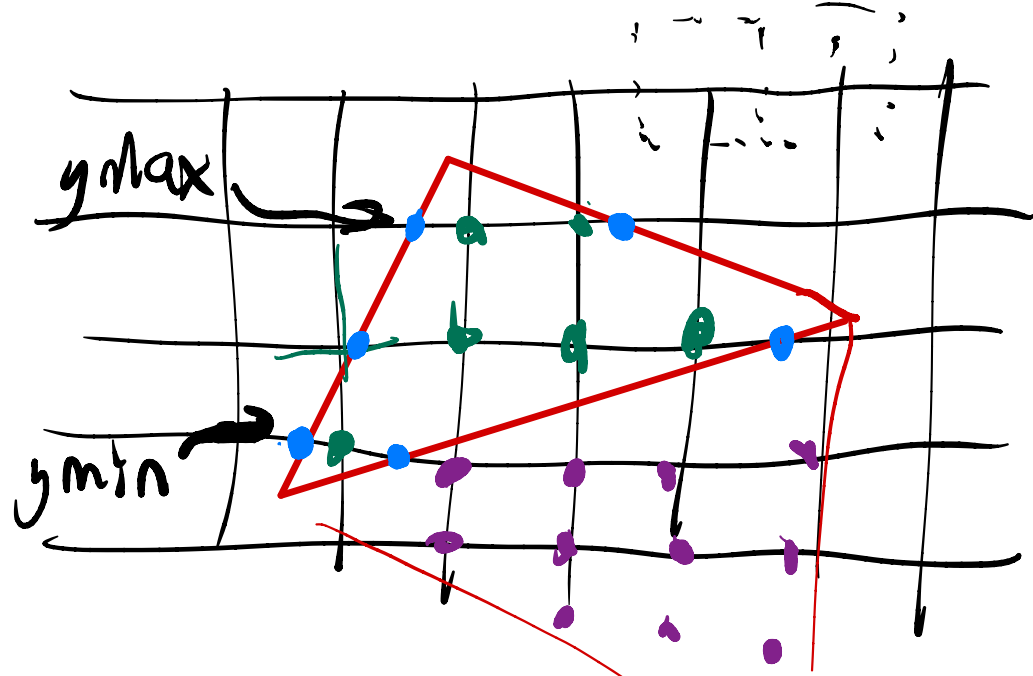
fill in the horizontal line

\Rightarrow CPU's an "old" hardware

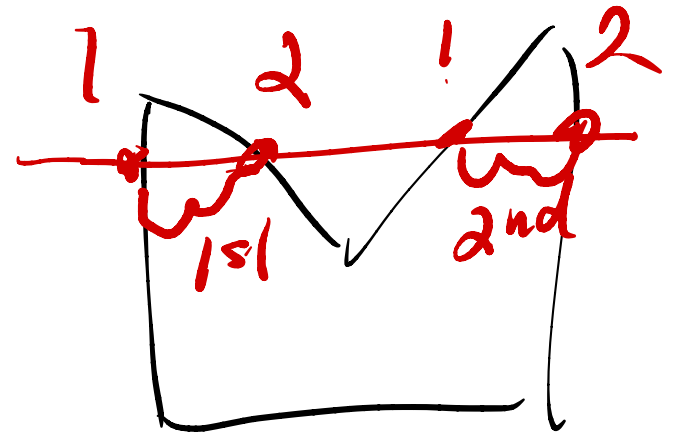


GPU's rasterization is done by "pixel"

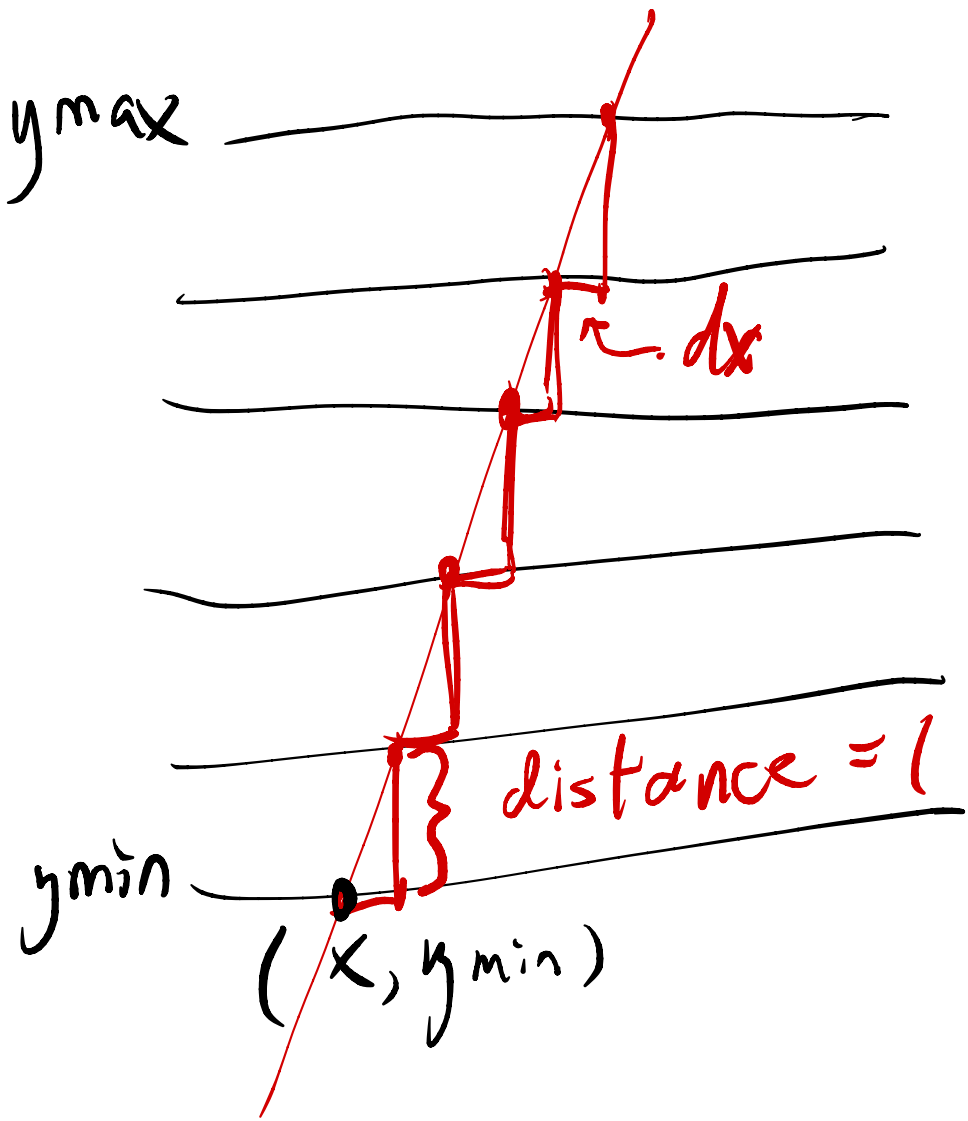
- separately scans "current display"



polygon raster



for ($y = y_{min}; y \leq y_{max}; y++$)
 for x-intersection for scanline & edges
 sort the set of line segments by x-values
 fill the pixels between intersections



y_{min} (integer)

edge : $\{x, dx\}$

↙

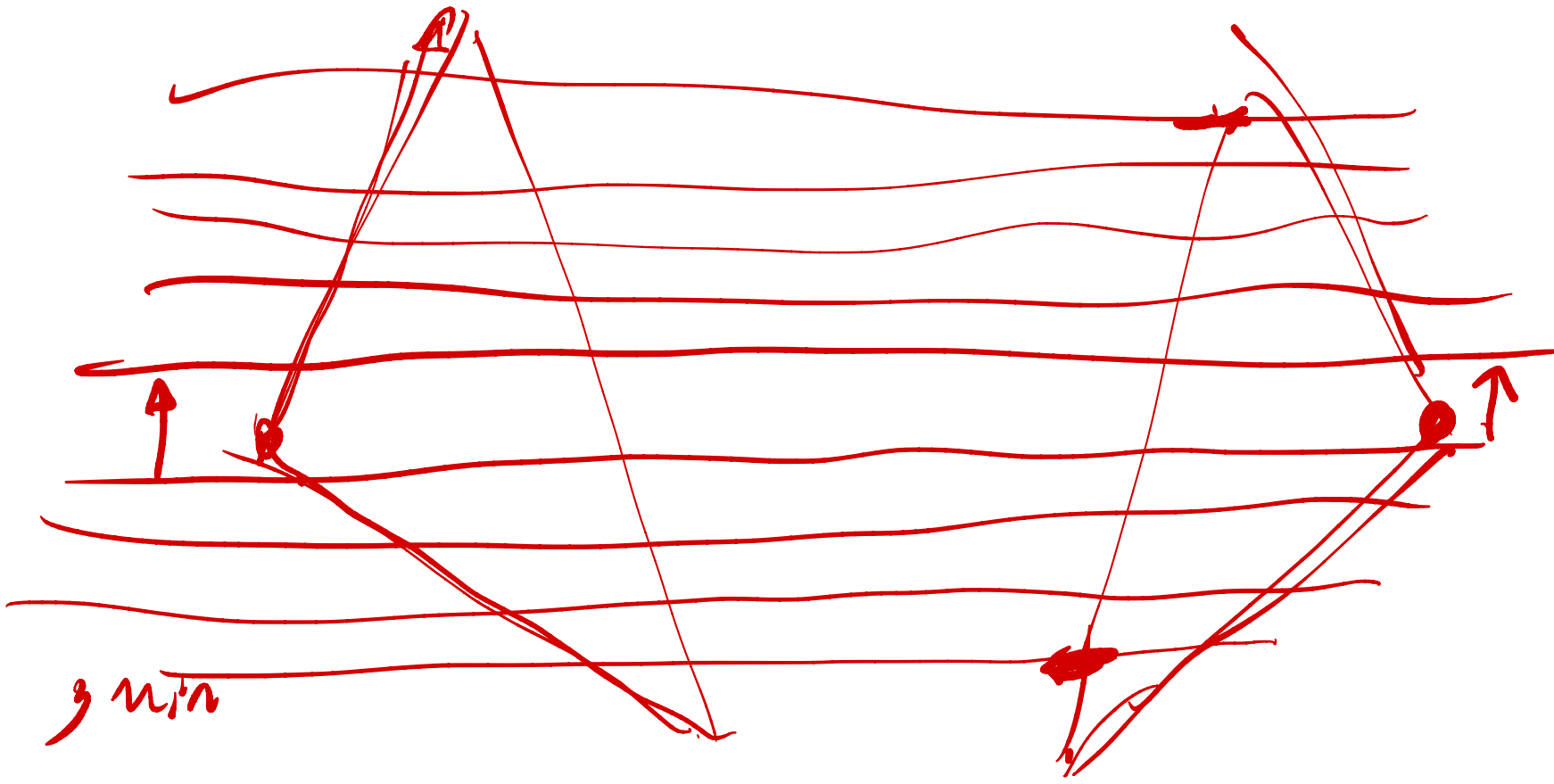
intersection of edge
with y_{min}

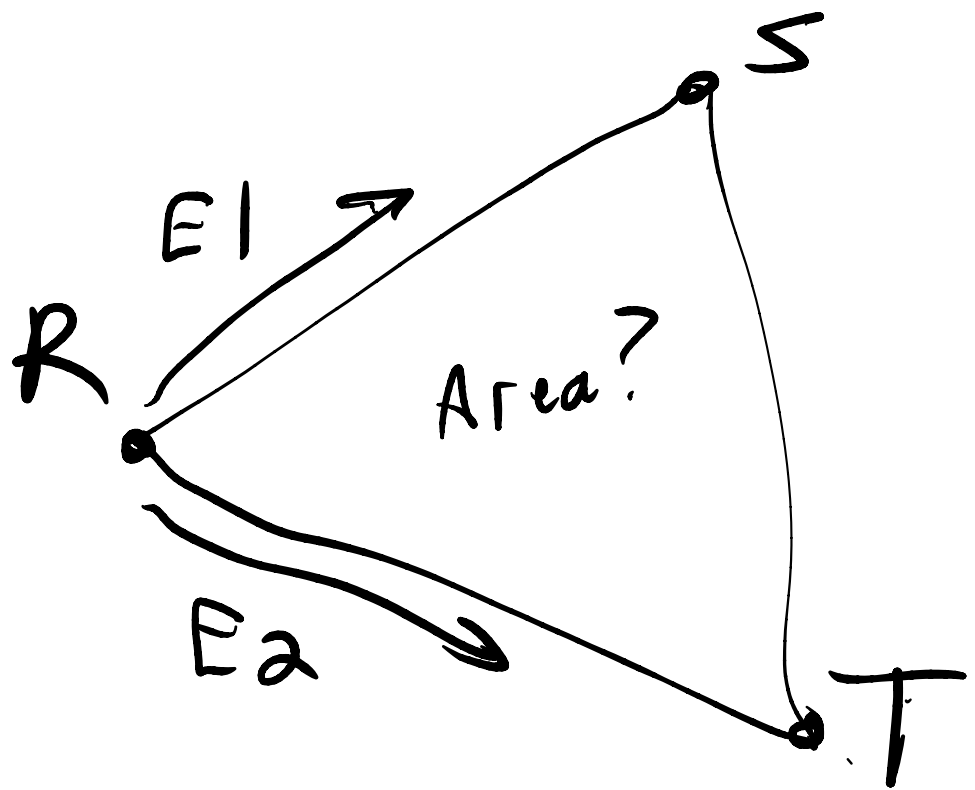
```
find  $y_{min}$ ,  $y_{max}$   
find  $x_{left}$ ,  $x_{right}$ ,  $dx_{left}$ ,  $dx_{right}$   
for ( $y = y_{min}$ ,  $y \leq y_{max}$ ;  $y++$ ) {  
    for ( $x = \text{ceil}(x_{left})$ ;  $x < x_{right}$ ;  $x++$ )  
        write Pixel( $x, y, r, g, b$ )
```

```
    maybe-switch( $C$ );  
     $x_{left} += dx_{left}$   
     $x_{right} += dx_{right}$ 
```

By rows
(CPU)

}





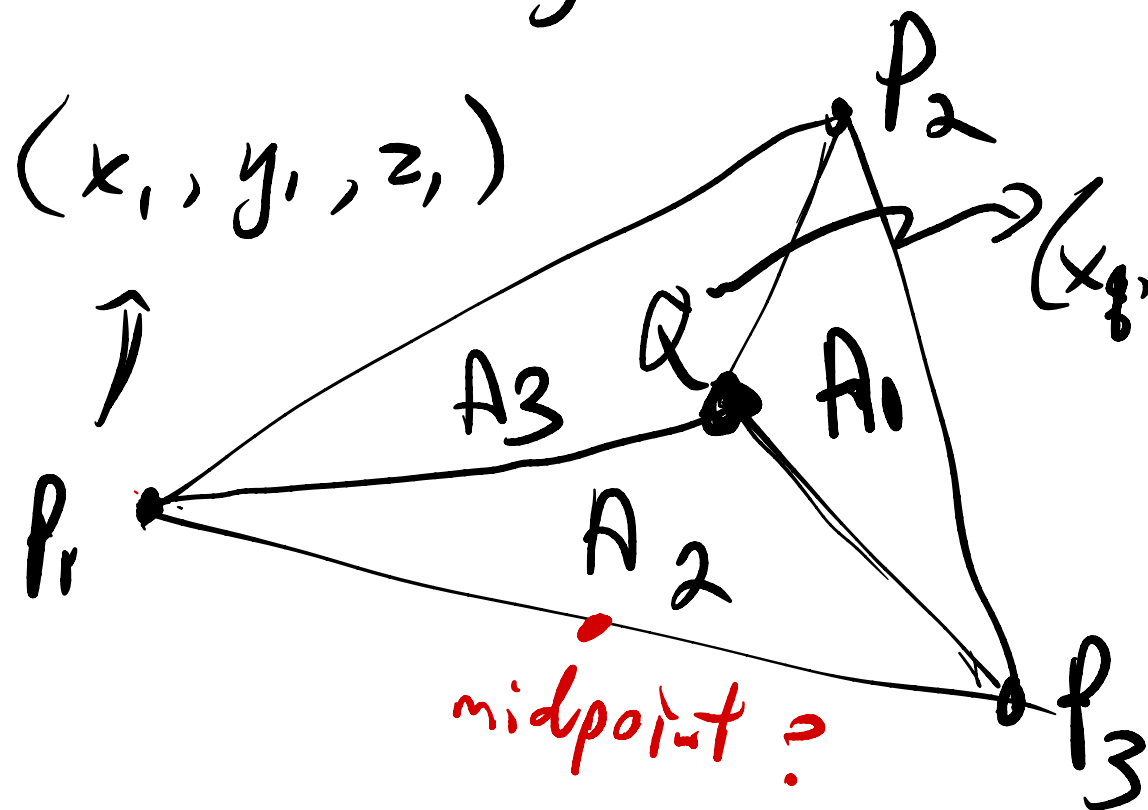
Triangle Area.

$$E_1 = S - R$$

$$E_2 = T - R$$

$$\text{Area}(R, S, T) = \frac{1}{2} \|\underbrace{E_1 \times E_2}_{\text{magnitude}}\|$$

Barycentric Coordinates



$A_1 =$ area of sub-triangle opposite P_1
 $(A_2, A_3) \dots$

$$A = A_1 + A_2 + A_3$$

$$\alpha = A_1 / A$$

$$\beta = A_2 / A$$

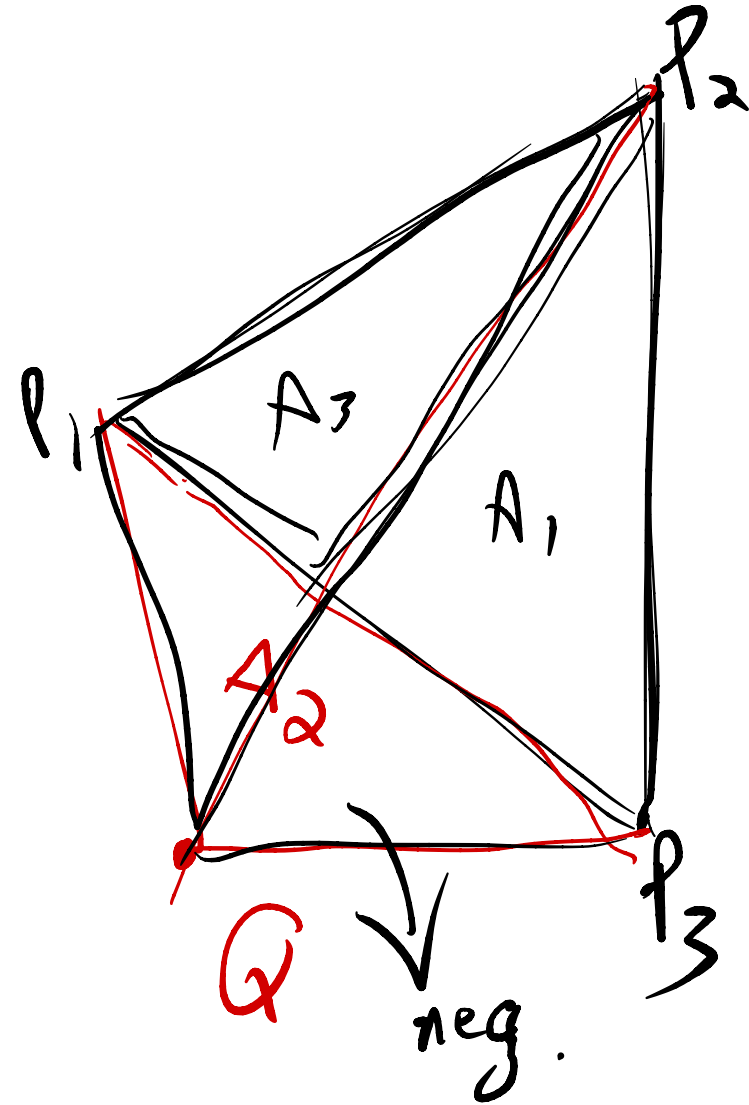
$$\gamma = A_3 / A$$

$$\alpha + \beta + \gamma = 1$$

$$Q = \alpha P_1 + \beta P_2 + \gamma P_3$$

$$Q = \alpha P_1 + \beta B_2 + \gamma P_3$$

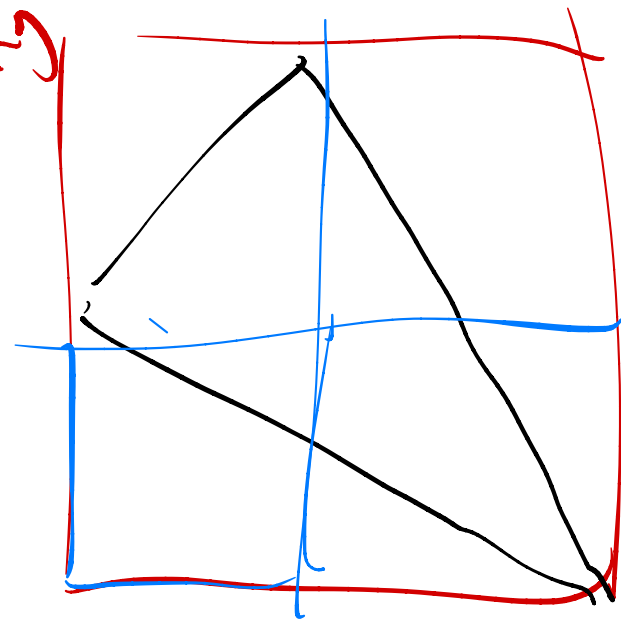
α, β, γ are positive inside
tri
one or more negative if point
is outside



find $x_{min}, y_{min}, x_{max}, y_{max}$

```
for (y = y_min, y < y_max, y++)  
  for (x = x_min, x < x_max, x++)  
    if (x, y inside triangle)  
      draw pixel()
```

Bounding
box



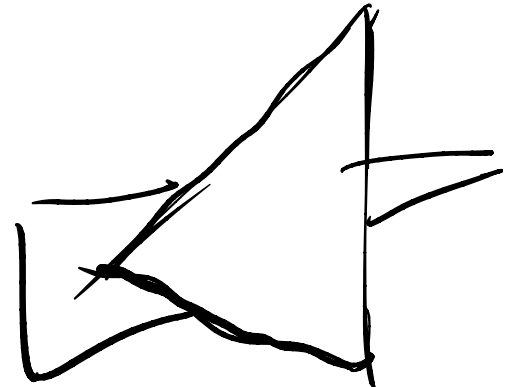
4 processors

GPU

Hidden Surfaces / Visible Surfaces

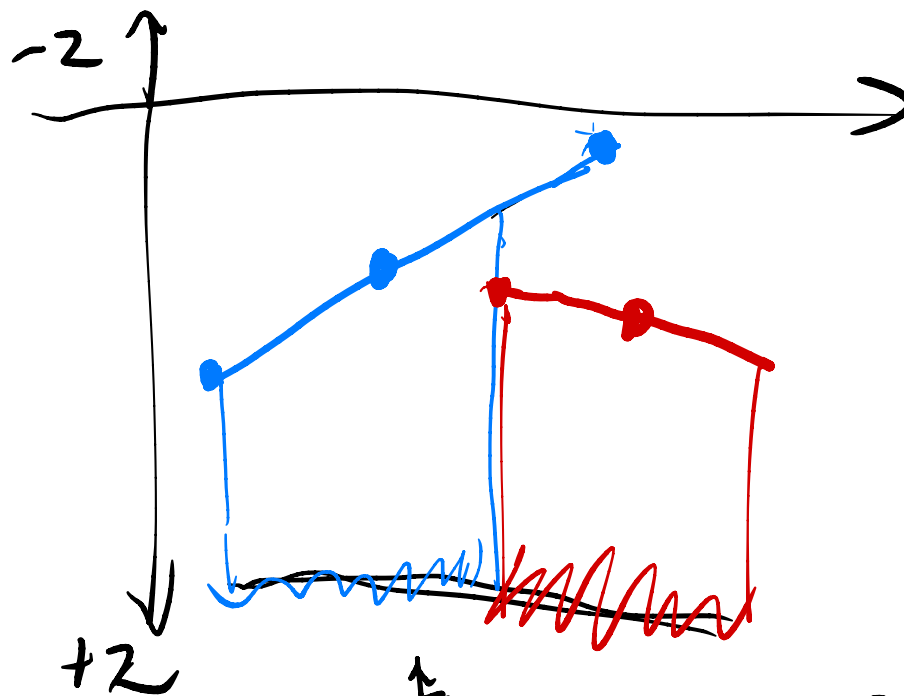
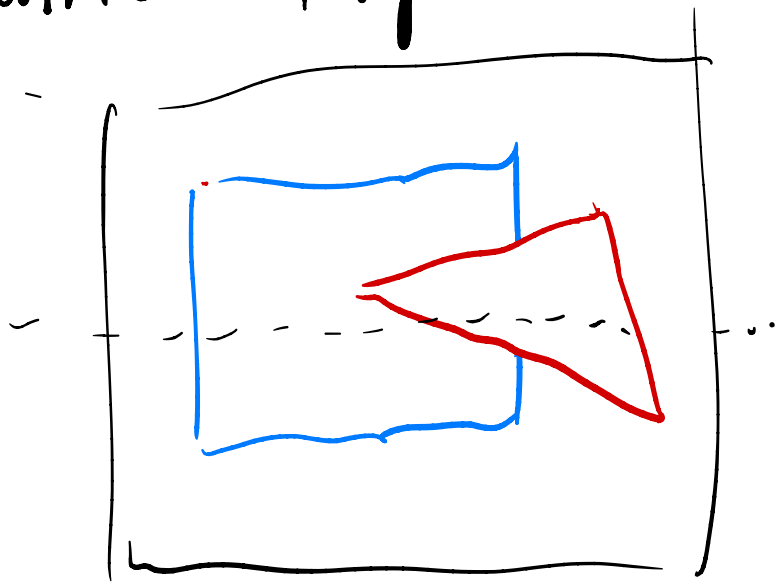
used to be a big problem

4 common Hidden Surface Algorithms

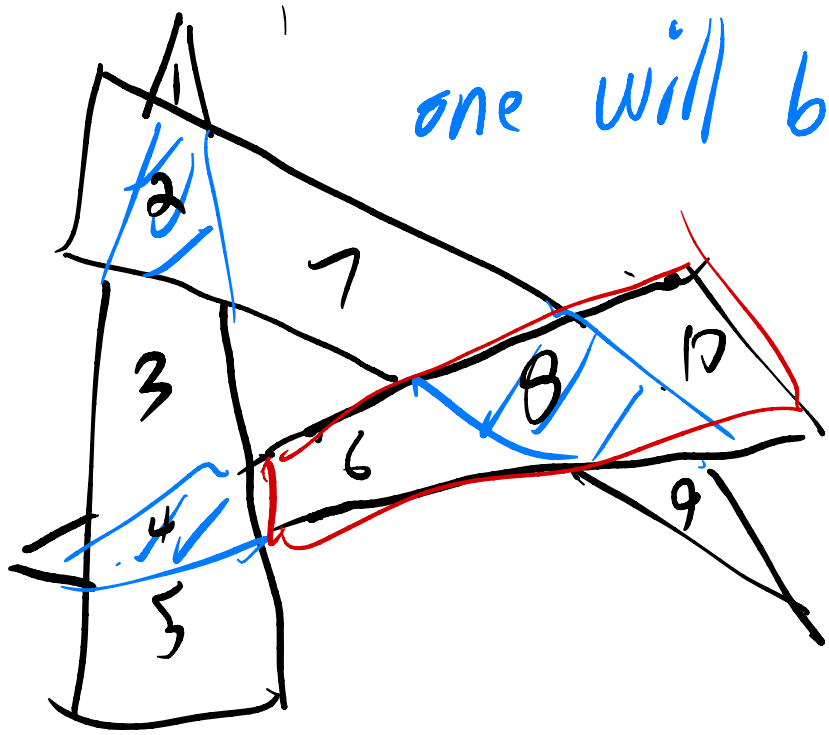


- Painter's Algorithm
- BSP-trees (Binary Space Partition)
- Z-buffer ← GPUs (fast)
- Ray tracing ← films, offline techniques (slower)

Painter's Alg



first sort polygons z . (z midpoint)
draw back to front in z



one will be wrong

BSP try to fix

z-buffering
framebuffer with r, g, b values per pixel (2^{255} / 8-bits per r, g, b)
add z (separate "z-buffer")
(add more data into framebuffer) 32-bits per pixel

take rasterization alg's for lines & triangles
we had DrawPixel(x, y, r, g, b)
now \rightarrow DrawPixel(x, y, z, r, g, b)

let p_z = z-value at (x, y) in z-buffer
if ($p_z <$ passed in z value)
WritePixel()
Write z()

No matter what order I draw, the closest pixel (on some triangle) will be display.

Built into GPU's

transparency is BIG Problem

- draw opaque objects first
- sort trans objects (Painter)
- draw back to front